

Shifted Chybeshev Polynomials for a Certain System of Fractional Order Integro-Differential Equations

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Abstract

The main goal of this paper lies briefly in submitting and modifying some numerical methods for solving system of linear Fractional order Integro- Differential Equations of Fredholm type (L.FFIDE's). in this method four kinds of shifted Chybeshev polynomials (T^*, U^*, V^* and W^*) are used as a bases of independed polynomials approximation $f_n(x)$. The general fractional derivatives of these polynomials are formulated ($D^a T_n^*, D^a U_n^*, D^a V_n^*$ and $D^a W_n^*$) in the framework of the Riemann-liouville definition. Some numerical examples are solving to show that the different between these polynomials, furthermore Algorithms and programs by using MATLAB program are given.

Keywords : Shifted Chybeshev Polynomials, System of fractional integro-differential equations.

دوال شيبشيف المعدلة لحل نظام محدد لمعادلات تكاملية تفاضلية كسورية

الخلاصة

الهدف الاساسي من هذا البحث هو تقديم وتطوير بعض الطرق العددية لحل نظام المعادلات التفاضلية التكاملية الكسورية الخطية من النوع فريدهولم. استخدمت اربعة انواع من الدوال المتعامدة شيبشيف كدوال لتقريب الدوال المجهولة. تم ايجاد المشتقات الكسورية لهذه الدوال الاربعة باستخدام تعريف ريمان. تم اعطاء بعض الامثلة التوضيحية لبيان الفروقات في النتائج بين دوال التقريب. علاوة على ذلك تم اعطاء خطوات الحل المتبعة في ايجاد الحل العددي باستخدام برنامج الماتلاب.

1-Introduction

Fractional calculus is the field of mathematical analysis which deals with the investigation and applications of integrals and derivatives of arbitrary order (real and complex numbers). The term fractional is a misnomer, but it is retained following the prevailing use.

System of fractional integro-differential equations are equations having unknown function together

with both fractional differential and integral operations and has the form:

$$D_x^a f^i(x) = g^i(x) + \sum_{j=1}^m \int_a^b k_{ij}(x,t) f^j(t) dt$$

$$i=1,2,\dots,m ; a \leq x \leq b$$

The theory and application of fractional integral and derivatives can be fund in many fields of science and engineering, such as Viscoelasticity, fractional differential which have been used to describe material's

constitutive equations. In fact a well-known equation which contains a fractional integral operator is the Abel integral equation.[1,2,4,5,9].

2-Basic Definitions: In this section we give definitions:

2-1 Definition: the fractional derivative by Reimaan-Lovill (R-L) has the form:

$$D_x^a F(x) = \begin{cases} \frac{d^n}{dt^n} \left[\frac{1}{\Gamma(m-a)} \int_0^t (t-x)^{m-a-1} F(x) dx \right] & m-1 < a < m \\ \frac{d^n}{dt^n} F(x) & m=a \end{cases}$$

Where *m* is an integer number less than *a*. [3, 5, 7]

Note: In this paper, we use *R-L* definition and its properties to find fractional derivatives of polynomials.

2-2 Some important properties of operator (D_x^a) [7,8]:

a-
$$D_x^a \sum c_i f_i(x) = \sum c_i D_x^a f_i(x)$$

the linearity property.

b-
$$D_x^a c = \frac{c}{\Gamma(n-a)} \frac{d^n}{dx^n} \left(\frac{x^{n-a}}{n-a} \right)$$

where *c* is constant.

c-
$$D_x^a x^m = \frac{m!}{\Gamma(m-a+1)} x^{m-a}$$

where *m*=0, 1, 2,..., *a* > 0.

In a special case, *a* =0.5 we have:

d-
$$D_x^{0.5} c = \frac{c}{\sqrt{p} x}$$

e-
$$D_x^{0.5} x^m = \frac{(m!)^2 (4x)^m}{(2m)! \sqrt{p} x}$$

m=0, 1, 2,...

3- Chebyshev polynomials [3]: Chebyshev polynomials are orthogonal functions, and every where dense in numerical analysis.

These polynomials have four kinds and have the forms:

3-1 First kind $T_n(x)$ is a polynomial in *x* of degree *n*. Defined by the relation:

$$T_n(x) = \cos(n\theta) \quad \text{where } x = \cos \theta \quad \dots(1)$$

The range of the variable *x* is the interval [-1,1], and the range of *θ* can be taken as [0,π].

The recurrence relation:

$$T_n(x) = 2xT_{n-1}(x) - T_{n-2}(x) \quad ; \quad n=2, 3, \dots \quad \text{where } T_0(x) = 1 \text{ and } T_1(x) = x \quad \dots(2)$$

The general form given by:

$$T_n(x) = \frac{n}{2} \sum_{r=0}^{[n/2]} (-1)^r \frac{(n-r-1)!}{r!(n-2r)!} (2x)^{(n-2r)} ; T_0(x) = 1 ; n > 1 \quad \dots(3)$$

3-2 Second kind polynomial $U_n(x)$:

It is a polynomial of degree *n* in *x* defined by:

$$U_n(x) = \frac{\sin(n+1)\theta}{\sin \theta} \quad \text{where } x = \cos \theta \quad \dots(4)$$

The recurrence relation:

$$U_n(x) = 2xU_{n-1}(x) - U_{n-2}(x) \quad ; \quad n=2,3, \dots \quad \text{where } U_0(x) = 1 ; U_1(x) = 2x \quad \dots(5)$$

The general form:

$$U_n(x) = \sum_{r=0}^{[n/2]} (-1)^r \frac{(n-r)!}{r!(n-2r)!} (2x)^{(n-2r)} ;$$

$$U_0(x) = 1 ; n > 1 \quad \dots(6)$$

3-3 Third kind polynomial $V_n(x)$:

Are polynomials of degree *n* in *x* defined by:

$$V_n(x) = \cos(n+1/2)\theta / \cos(1/2)\theta \quad \text{Where } x = \cos \theta \quad \dots(7)$$

The recurrence relation:

$$V_n(x) = 2xV_{n-1}(x) - V_{n-2}(x) \quad ; \quad n=2,3, \dots \quad \text{where } V_0(x) = 1 ; V_1(x) = 2x-1 \quad \dots(8)$$

3-4 Fourth kind polynomial $W_n(x)$: are polynomials of degree *n* in *x* defined by :

$$W_n(x) = \frac{\sin(n+1/2)\theta}{\sin(1/2)\theta} \quad \text{where } x = \cos \theta \quad \dots(9)$$

The recurrence relation:

$$\begin{aligned} W_n(x) &= 2xW_{n-1}(x) - W_{n-2}(x) ; \\ n=2,3,.. \quad \text{Where } W_0(x) &= 1 ; \\ W_1(x) &= 2x+1 \quad \dots(10) \end{aligned}$$

4-Connections between the four kinds of polynomials:

Since $\sin(n+1)\theta - \sin(n-1)\theta = 2\sin\theta \cos n\theta$ we have :

$$\begin{aligned} U_n(x) - U_{n-2}(x) &= 2T_n(x) ; \\ n=2,3,.. \quad \text{where } U_0(x) &= T_0(x) = 1 \quad \dots(11) \end{aligned}$$

$$U_n(x) = 1/2 [V_n(x) + W_n(x)] \quad n=2,3,.. \quad \dots(12)$$

Since the trigonometric relations

$$2 \sin(1/2 \theta) \cos(n+1/2)\theta = \sin(n+1)\theta - \sin(n\theta)$$

$$2 \cos(1/2 \theta) \sin(n+1/2)\theta = \sin(n+1)\theta + \sin(n\theta)$$

We have

$$V_n(x) = U_n(x) - U_{n-1}(x) \quad \text{where } U_0(x)=1 ; U_1(x)=2x \quad \dots(13)$$

$$W_n(x) = U_n(x) + U_{n-1}(x) \quad \text{where } U_0(x)=1 ; U_1(x)=2x \quad \dots(14)$$

5-The shifted Chebyshev polynomials (T_n^*, U_n^*, V_n^* and W_n^*)

[10] :

Since the range [0,1] is quite often more convenient to use than range [-1,1] , we sometimes map the independent variable x in [0,1] to the variable s in [-1,1] by the transformations

$$S = 2x-1 \quad \text{or } x = 1/2 (1+s) \quad \dots (15)$$

Using the variable s into equations above (3,6,13 and 14) we have four forms of shifted Chebyshev polynomials,eq's (16-19).

$$T_n^*(x) = T_n(s); \quad U_n^*(x) = U_n(s);$$

$$V_n^*(x) = V_n(s); \quad W_n^*(x) = W_n(s)$$

where $s=2x-1$

And the general forms:

$$\begin{aligned} T_n^*(x) &= \frac{n}{2} \sum_{r=0}^{[n/2]} (-1)^r \frac{(n-r-1)!}{r!(n-2r)!} (2s)^{(n-2r)} ; \\ T_0(s) &= 1 ; n > 1 \quad \dots(16) \end{aligned}$$

$$\begin{aligned} U_n^*(x) &= \sum_{r=0}^{[n/2]} (-1)^r \frac{(n-r)!}{r!(n-2r)!} (2s)^{(n-2r)} ; \\ U_0(s) &= 1 ; n > 1 \quad \dots(17) \end{aligned}$$

$$V_n^*(x) = U_n(s) - U_{n-1}(s) \quad \text{where } U_0(s)=1 ; U_1(s)=2s \quad \dots(18)$$

$$W_n^*(x) = U_n(s) + U_{n-1}(s) \quad \text{where } U_0(s)=1 ; U_1(s)=2s \quad \dots(19)$$

6- Fractional Derivatives of shifted Chebyshev polynomials:

Consider the properties of the operator (D_x^a) eq's(1-2 a, b, and c) putting in eq's (16,17,18 and 19) yield:

$$\begin{aligned} D_x^a T_n^*(x) &= \frac{n}{2} \sum_{r=0}^{[n/2]} (-1)^r \frac{\Gamma(n-r)(2)^{(n-2r)}}{r!\Gamma(n-2r+a)} (s)^{(n-2r-a)} ; \\ &n > 1 \quad \dots(20) \end{aligned}$$

$$\begin{aligned} \text{where } D_x^a T_0^*(x) &= \frac{1}{\Gamma(n-a)} \frac{d^n}{dx^n} \left(\frac{s^{n-a}}{n-a} \right); \quad \text{where} \\ s &= 2x-1 \quad \dots(20a) \end{aligned}$$

$$\begin{aligned} D_x^a U_n^*(x) &= \sum_{r=0}^{[n/2]} (-1)^r \frac{\Gamma(n-r)(2)^{(n-2r)}}{r!\Gamma(n-2r+a)} (s)^{(n-2r-a)} ; n \\ &> 1 \quad \dots(21) \end{aligned}$$

$$\begin{aligned} \text{where } D_x^a U_0^*(x) &= \frac{1}{\Gamma(n-a)} \frac{d^n}{dx^n} \left(\frac{s^{n-a}}{n-a} \right); \quad \text{for } s=2x- \\ &\dots(21a) \end{aligned}$$

$$D_x^a V_n^*(x) = D_x^a U_n(s) - D_x^a U_{n-1}(s) \text{ where } s=2x-1 \dots(22)$$

$$D_x^a W_n^*(x) = D_x^a U_n(s) + D_x^a U_{n-1}(s) \text{ where } s=2x-1 \dots(23)$$

Where $U_0(s)$ and $U_1(s)$ from eq's(17) respectively.

REMARK 6-1: If $\alpha = 0.5$ and using properties of operator (D_x^a) eq's(c and d) then the general forms of fractional derivative of shifted Chebyshev polynomials yield:

$$D_x^{0.5} T_0^*(x) = \frac{1}{\sqrt{ps}}; \text{ where } s=2x-1 \dots(24)$$

$$D_x^{0.5} U_0^*(x) = \frac{1}{\sqrt{ps}}; \text{ where } s=2x-1 \dots(25)$$

7- System of Linear Fractional Integro-Differential Equation of Fredholm type (S.LFFIDE's): This system is given by the form [6]:

$$D_x^a f^i(x) = g^i(x) + \sum_{j=1}^m \int_a^b k_{ij}(x,t) f^j(t) dt \text{ ; } i=1,2,\dots,m ; a \leq x \leq b \dots(26)$$

The system has (m) independent equations, Any equation has (m) unknown functions $f^i(x)$. For example let $m=2$ the system eq(26) gives two the following equations:

$$D_x^a f^1(x) = g^1(x) + \int_a^b \{k_{11}(x,t) f^1(t) + k_{12}(x,t) f^2(t)\} dt$$

$$D_x^a f^2(x) = g^2(x) + \int_a^b \{k_{21}(x,t) f^1(t) + k_{22}(x,t) f^2(t)\} dt$$

8- Solving the system of (S.LFFIDE's): In this section we give a numerical method to solve this

system (i.e find unknown functions $f^i(x)$) by using two steps:

Step1: We approximate unknown functions by (N) known functions (Φ_r) by the form:

$$f^i(x) \approx f_N^i(x) = \sum_{r=0}^N c_r^i \Phi_r \dots(27)$$

The important conditions (the known functions (bases) Φ_r must be linearly independent) so that in this work we choose orthogonal functions $(T_n^*, U_n^*, V_n^*$ and $W_n^*)$ as a bases functions.

Butting eq(27) in eq(26) yields eq (28), that is to give a system of (M) equations with (m(N+1)) unknown parameters (C_r^i) , we must found them to find solution of the system.

$$D_x^a \sum_{r=0}^N c_r^i \Phi_r^i(x) = g^i(x) + \sum_{j=1}^m \int_a^b k_{ij}(x,t) \sum_{r=0}^N c_r^j \Phi_r^j(t) dt \text{ ; } i=1,2,\dots,m ; a \leq x \leq b \dots(28)$$

Step2: In this step we choose (N) points (x_k) in the interval [a,b] i.e $(a \leq x_0 < x_1 < \dots < x_N \leq b)$, putting these points in the system equations (28) we have system eq(29) which gives (m(N+1)) independent equations with (m(N+1)) unknown parameters

(C_r^i) , solve this system using Gausse-Elimination.

$$\sum_{r=0}^N c_r^i D_x^a \Phi_r^i(x_k) - \sum_{j=1}^m \sum_{r=0}^N c_r^j \int_a^b K_{ij}(x,t) \Phi_r^j(t_k) dt = g^i(x_k) \text{ ; } i=1,2,\dots,M ; k=0,1,\dots,N \dots(29)$$

Remark8-1: We can write the system of eq(29) by a matrix from as:

$$AC = G \dots(30)$$

where A is (m(N+1)) by (m(N+1)) matrix contains (m by m) sub-

matrices (A_{ij}^{rk}) where $I, j=1,2,\dots,m$;
 $r,k=0,1,2,\dots,N$ we can write as:

$$A = \begin{bmatrix} A_{11}^{rk} & A_{12}^{rk} & \dots & A_{1m}^{rk} \\ A_{21}^{rk} & A_{22}^{rk} & \dots & A_{2m}^{rk} \\ \cdot & \cdot & \dots & \cdot \\ \cdot & \cdot & \dots & \cdot \\ A_{m1}^{rk} & A_{m2}^{rk} & \dots & A_{mm}^{rk} \end{bmatrix} \quad \text{where} \quad r,k = 0,1,2,\dots,N \quad \dots(31)$$

Where the sub-matrices are:

$$A_{ij} = \begin{bmatrix} a_{ij}^{00} & a_{ij}^{01} & \dots & a_{ij}^{0N} \\ a_{ij}^{10} & a_{ij}^{11} & \dots & a_{ij}^{1N} \\ \cdot & \cdot & \dots & \cdot \\ \cdot & \cdot & \dots & \cdot \\ a_{ij}^{N0} & a_{ij}^{N1} & \dots & a_{ij}^{NN} \end{bmatrix} \quad \text{where}$$

the elements (a_{ij}^{rk}) from eq(33)

$$(a_{ij}^{rk}) = \begin{cases} D_x^a \Phi_r(x_k) - \int_a^b k_{ii}(x_k, t) \Phi_k(x_k) dt & \text{if } i = j \\ - \int_a^b k_{ij}(x_k, t) \Phi_k(x_k) dt & \text{if } i \neq j \end{cases} \quad \dots(33)$$

The C column has m sub-columns (C_r^i) and we can write them as:

$$C = \begin{bmatrix} C_r^1 \\ C_r^2 \\ \cdot \\ \cdot \\ C_r^m \end{bmatrix} \quad \text{where}$$

$$C_r^i = \begin{bmatrix} c_0^i \\ c_1^i \\ \cdot \\ \cdot \\ c_N^i \end{bmatrix} \quad \dots(34)$$

Similarly, we can write the G column by $(N+1)$ sub columns as:

$$G = \begin{bmatrix} g_k^1 \\ g_k^2 \\ \cdot \\ \cdot \\ g_k^m \end{bmatrix} \quad \text{where}$$

$$g_k^i = \begin{bmatrix} g_0^i \\ g_1^i \\ \cdot \\ \cdot \\ g_N^i \end{bmatrix} \quad \text{where } g_k^i = g^i(x_k) \quad \dots(35)$$

Remark 8-2: Since eq(33) and properties (d and e) of operator ($D_x^{0.5}$) then all parts of matrix (A) has

the part $(\frac{1}{\sqrt{p}x})$ so that we must

choose points $(x_k, k=0,1,2,\dots,N)$ s.t $(2x_k - 1 > 0)$ or $(x_k > 0.5)$, in general $x_k = 0.55 + k(0.45/N)$ $\dots(36)$

For example if $N=2$ then $k=0,1,2$ and $x_k=\{0.55,0.77,1\}$.

Algorithm: Steps to solve (S.LFFIDE's):

Step1: Choose points x_k use eq(36) where $k=0,1,\dots,N$.

Step2: Evaluate (a_{ij}^{rk}) use eq's(33) and eq's (16-19, 20-23) for all $i,j=1,2,\dots,m$;
 $k,r=0,1,2,\dots,N$.

Step3: compute g_k^i use eq(35) for all $i=1,2,\dots,m$; $k=0,1,\dots,N$.

Step4: construct the general matrix A use eq's(31-32) with step2 and column G using eq(35) with step3.

Step5: solve the system $AC = G$ use Gauss-Elmination to find column C where

$$C = A \setminus G \text{ or } C = \text{inv}(A) * G.$$

Step6: find the approximate solutions $f_N^i(x)$ use eq(27) where the bases functions Φ_r are one of bases $(T_n^*, U_n^*, V_n^* \text{ and } W_n^*)$.

Note: in this work we use programs in MATLAB with six steps above to find approximate solution where:

$F_N i T^*$ means programs use steps above to find approximate solution to $f^i(x)$.

$F_N i U^*$ means programs use steps above to find approximate solution to $f^i(x)$.

$F_N i V^*$ means programs use steps above to find approximate solution to $f^i(x)$.

$F_N i W^*$ means programs use steps above to find approximate solution to $f^i(x)$.

Example1: Solve the linear system (FFIDE's):

$$D_x^{0.5} f^i(x) = g^i(x) + \sum_{j=1}^2 \int_0^1 k_{ij}(x,t) f^j(t) dt$$

where $k_{ij}(x,t)=1$; $i,j=1,2$ and

$$g^1(x) = \frac{2x}{\sqrt{px}} - 1 \quad ;$$

$$g^2(x) = \frac{4x}{\sqrt{px}} - 0.5 \quad \text{with exact}$$

solution $f^1(x)=x$; $f^2(x)=2x$.

Solution: Choose $N=1$ and running four programs above the results of this example listed in tables (1-1), (1-2) which obtained by using bases $(T_n^*, U_n^*, V_n^* \text{ and } W_n^*)$.

Example 2: Solve the linear system (FFIDE's):

$$D_x^{0.5} f^i(x) = g^i(x) + \sum_{j=1}^2 \int_0^1 k_{ij}(x,t) f^j(t) dt$$

where $k_{ij}(x,t)=1$; $i,j=1,2$ and

$$g^1(x) = \frac{2x}{\sqrt{px}} - 3 \quad ;$$

$$g^2(x) = \frac{1}{\sqrt{px}} + \frac{4x}{\sqrt{px}} + \frac{8x^2}{\sqrt{px}} - 0.5$$

with exact solution $f^1(x)=x$; $f^2(x)=1+2x+3x^3$.

Solution: Choose $N=2$: and running four programs above the results of this example listed in tables (2-1), (2-2) which obtained by using bases $(T_n^*, U_n^*, V_n^* \text{ and } W_n^*)$.

Example 3: Solve the linear system (FFIDE's):

$$D_x^{0.5} f^1(x) = g^1(x) + \int_0^1 f^2(t) dt \quad ;$$

$$D_x^{0.5} f^2(x) = g^2(x) + \int_0^1 f^1(t) dt$$

$$g^1(x) = \frac{1}{\sqrt{px}} + e^x \text{erf}(\sqrt{x}) - (e^3 - e^2)$$

;

$$g^2(x) = \frac{1}{\sqrt{px}} + e^x \operatorname{erf}(\sqrt{x}) - (e-1)$$

with exact solution $f^1(x) = e^x$;
 $f^2(x) = e^{x+2}$.

Solution: Choose N=5,8 and running four programs above the results of this example listed in tables (3-1), (3-2) which obtained by using bases $(T_n^*, U_n^*, V_n^*$ and $W_n^*)$.

Conclusions

1. All kinds of shifted Chebyshev polynomials $(T_n^*, U_n^*, V_n^*$ and $W_n^*)$ as a basis function which are used in this paper have proved their effectiveness in solving linear system (FFIDE's) numerically and finding accurate results, when unknown functions are algebraic functions, other functions the U_n^* gives better solution than other bases.
2. All Chebyshev polynomials depends on N as N increasing, the error term is decreased.
3. The results show a marked improvement in the least square errors from which we conclude that.

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Ex1-(N1)

f1=x

X_i	F1=x	F _{N1} T	F _{N1} U	F _{N1} V	F _{N1} W
0.1	0.1	0.1	0.1	0.1	0.1
0.2	0.2	0.2	0.2	0.2	0.2
0.3	0.3	0.3	0.3	0.3	0.3
0.4	0.4	0.4	0.4	0.4	0.4
0.5	0.5	0.5	0.5	0.5	0.5
0.6	0.6	0.6	0.6	0.6	0.6
0.7	0.7	0.7	0.7	0.7	0.7
0.8	0.8	0.8	0.8	0.8	0.8
0.9	0.9	0.9	0.9	0.9	0.9
1	1	1	1	1	1
L.S. <u>Error</u>		0.0	0.0	0.0	0.0

Table(1-1)

f2=2x

X_i	F2=2x	F _{N2} T	F _{N2} U	F _{N2} V	F _{N2} W
0.1	0.2	0.2	0.2	0.2	0.2
0.2	0.4	0.4	0.4	0.4	0.4
0.3	0.6	0.6	0.6	0.6	0.6
0.4	0.8	0.8	0.8	0.8	0.8
0.5	1	1	1	1	1
0.6	1.2	1.2	1.2	1.2	1.2
0.7	1.4	1.4	1.4	1.4	1.4
0.8	1.6	1.6	1.6	1.6	1.6
0.9	1.8	1.8	1.8	1.8	1.8
1	2	2	2	2	2
L.S. <u>Error</u>		0.0	0.0	0.0	0.0

Table(1-2)

Ex2:

$$f1=x$$

X	f1=x	F _{1T}	F _{1U}	F _{1V}	F _{1W}
0.1	0.1	9.99999999993704e-002	9.9999999999347e-02	9.99999999998016e-002	9.99999999998777e-002
0.2	0.2	1.99999999999305e-001	1.9999999999929e-01	1.99999999999784e-001	1.99999999999863e-001
0.3	0.3	2.99999999999242e-01	2.9999999999924e-01	2.99999999999767e-001	2.99999999999849e-001
0.4	0.4	3.99999999999181e-01	3.9999999999919e-01	3.99999999999750e-001	3.99999999999834e-001
0.5	0.5	4.99999999999122e-01	4.9999999999914e-01	4.99999999999734e-001	4.99999999999821e-001
0.6	0.6	5.99999999999065e-01	5.9999999999909e-01	5.99999999999718e-001	5.99999999999808e-001
0.7	0.7	6.99999999999010e-01	6.9999999999903e-01	6.99999999999702e-001	6.99999999999796e-001
0.8	0.8	7.99999999998956e-01	7.9999999999898e-01	7.99999999999687e-001	7.99999999999785e-001
0.9	0.9	8.99999999998904e-01	8.9999999999894e-01	8.99999999999672e-001	8.99999999999774e-001
1	1	9.99999999998853e-01	9.9999999999889e-01	9.99999999999657e-001	9.99999999999764e-001
L.S. Error		8.356225665870656e-026	8.147801643626350e-028	7.665109533443739e-027	3.472446447646524e-027

Table(2-1)

$$f2=1+2x+3x^2$$

X _i	F ₂ = 1+2x+3x ²	F _{2T}	F _{2U}	F _{2V}	F _{2W}
0.1	1.23	1.22999999999920e+000	1.2299999999992e+000	1.22999999999976e+000	1.22999999999982e+000
0.2	1.52	1.51999999999917e+000	1.5199999999992e+000	1.51999999999975e+000	1.51999999999982e+000
0.3	1.87	1.86999999999914e+000	1.8699999999992e+000	1.86999999999974e+000	1.86999999999982e+000
0.4	2.28	2.27999999999911e+000	2.2799999999991e+000	2.27999999999973e+000	2.27999999999981e+000
0.5	2.75	2.74999999999907e+000	2.7499999999991e+000	2.74999999999973e+000	2.74999999999981e+000
0.6	3.28	3.27999999999903e+000	3.2799999999991e+000	3.27999999999971e+000	3.27999999999980e+000
0.7	3.87	3.86999999999899e+000	3.8699999999990e+000	3.86999999999970e+000	3.86999999999979e+000
0.8	4.52	4.51999999999896e+000	4.5199999999990e+000	4.51999999999969e+000	4.51999999999978e+000
0.9	5.23	5.22999999999891e+000	5.2299999999990e+000	5.22999999999968e+000	5.22999999999977e+000
1	6.00	5.99999999999886e+000	5.9999999999989e+000	5.99999999999965e+000	5.99999999999976e+000
L.S. Error		9.253832949302878e-026	8.664819360241697e-028	8.171885548270880e-027	4.025995491859953e-027

Table (2-2)

Ex3-(N=5)

$$f1=e^x$$

X_i	$F1=e^x$	F_{p1T}	F_{p1U}	F_{p1V}	F_{p1W}
0.1	1.1052	1.217173618485968e+000	1.217173618485225e+000	1.217173618484390e+000	1.217173618485821e+000
0.2	1.2214	1.348808726382611e+000	1.348808726381767e+000	1.348808726380817e+000	1.348808726382442e+000
0.3	1.3499	1.492138425910013e+000	1.492138425909072e+000	1.492138425908013e+000	1.492138425909823e+000
0.4	1.4918	1.648301689258319e+000	1.648301689257285e+000	1.648301689256121e+000	1.648301689258109e+000
0.5	1.6487	1.818649813975645e+000	1.818649813974523e+000	1.818649813973262e+000	1.818649813975416e+000
0.6	1.8221	2.004746422968084e+000	2.004746422966880e+000	2.004746422965525e+000	2.004746422967838e+000
0.7	2.0138	2.208367464499703e+000	2.208367464498420e+000	2.208367464496977e+000	2.208367464499440e+000
0.8	2.2255	2.431501212192541e+000	2.431501212191184e+000	2.431501212189658e+000	2.431501212192263e+000
0.9	2.4696	2.676348265026113e+000	2.676348265025184e+000	2.676348265023579e+000	2.676348265026320e+000
1	2.7183	2.945321547339905e+000	2.945321547338409e+000	2.945321547336728e+000	2.945321547339598e+000
L.S. Error		3.145498694500295e-001	3.145498694458787e-001	3.145498694412111e-001	3.145498694491827e-001

Table (3-1)

$$e^{x+2}$$

X_i	$F2=e^{x+2}$	F_{p2T}	F_{p2U}	F_{p2V}	F_{p2W}
0.1	8.1662	8.344570670485336e+000	8.344570670484179e+000	8.344570670482883e+000	8.344570670485091e+000
0.2	9.0250	9.197138861722015e+000	9.197138861720880e+000	9.197138861719605e+000	9.197138861721777e+000
0.3	9.9742	1.014661385324100e+001	1.014661385323986e+001	1.014661385323857e+001	1.014661385324076e+001
0.4	11.0232	1.119996602222405e+001	1.119996602222288e+001	1.119996602222156e+001	1.119996602222380e+001
0.5	12.1825	1.236588185161165e+001	1.236588185161044e+001	1.236588185160907e+001	1.236588185161140e+001
0.6	13.4637	1.365476393010303e+001	1.365476393010177e+001	1.365476393010035e+001	1.365476393010277e+001
0.7	14.8797	1.507873095215615e+001	1.507873095215484e+001	1.507873095215336e+001	1.507873095215588e+001
0.8	16.4446	1.665161771798768e+001	1.665161771798632e+001	1.665161771798478e+001	1.665161771798740e+001
0.9	18.1741	1.838897513357305e+001	1.838897513357164e+001	1.838897513357004e+001	1.838897513357276e+001
1	20.0855	2.030807021064640e+001	2.030807021064493e+001	2.030807021064328e+001	2.030807021064610e+001
L.S. Error		3.707334532658249e-001	3.707334532609456e-001	3.707334532554368e-001	3.707334532648115e-001

Table (3-2)

Ex3-(N=8)

$$f2 = e^{x+2}$$

X_i	$F2=e^{x+2}$	F_{p2T}	F_{p2U}	F_{p2V}	F_{p2W}
0.1	8.1662	8.165948783324557e+000	8.165948783324557e+000	8.165948782393510e+000	8.165948783324557e+000
0.2	9.0250	9.024811590257933e+000	9.024811590257933e+000	9.024811589400859e+000	9.024811590257933e+000
0.3	9.9742	9.973982603730176e+000	9.973982603730176e+000	9.973982602882709e+000	9.973982603730176e+000
0.4	11.0232	1.102297143739168e+001	1.102297143739168e+001	1.102297143652431e+001	1.102297143739168e+001
0.5	12.1825	1.218228122197784e+001	1.218228122197784e+001	1.218228122107844e+001	1.218228122197784e+001
0.6	13.4637	1.346351658439830e+001	1.346351658439830e+001	1.346351658346254e+001	1.346351658439830e+001
0.7	14.8797	1.487950131679788e+001	1.487950131679788e+001	1.487950131582455e+001	1.487950131679788e+001
0.8	16.4446	1.644440741892184e+001	1.644440741892184e+001	1.644440741791092e+001	1.644440741892184e+001
0.9	18.1741	1.817389719711830e+001	1.817389719711830e+001	1.817389719607026e+001	1.817389719711830e+001
1	20.0855	2.008528010331039e+001	2.008528010331039e+001	2.008528010222593e+001	2.008528010331039e+001
L.S. Error		4.456612083042770e-007	4.456612083042770e-007	4.456651790039209e-007	4.456612083042770e-007

Table (4-2)

$$f1 = e^x$$

X_i	$F1=e^x$	F_{p1T}	F_{p1U}	F_{p1V}	F_{p1W}
0.1	1.1052	1.105050268611320e+000	1.105050268611320e+000	1.105050268102487e+000	1.105050268611320e+000
0.2	1.2214	1.221261937817951e+000	1.221261937817951e+000	1.221261937223005e+000	1.221261937817951e+000
0.3	1.3499	1.349698604926968e+000	1.349698604926968e+000	1.349698604250336e+000	1.349698604926968e+000
0.4	1.4918	1.491646427429108e+000	1.491646427429108e+000	1.491646426676433e+000	1.491646427429108e+000
0.5	1.6487	1.648526276731655e+000	1.648526276731655e+000	1.648526275908515e+000	1.648526276731655e+000
0.6	1.8221	1.821908273662720e+000	1.821908273662720e+000	1.821908272774079e+000	1.821908273662720e+000
0.7	2.0138	2.013527655690326e+000	2.013527655690326e+000	2.013527654740413e+000	2.013527655690326e+000
0.8	2.2255	2.225302200197914e+000	2.225302200197914e+000	2.225302199190300e+000	2.225302200197914e+000
0.9	2.4596	2.459351428157911e+000	2.459351428157911e+000	2.459351427095637e+000	2.459351428157911e+000
1	2.7183	2.718017812544971e+000	2.718017812544971e+000	2.718017811430656e+000	2.718017812544971e+000
L.S. Error		4.272778323838178e-007	4.272778323838178e-007	4.272813525296136e-007	4.272778323838178e-007

Table (4-1)